

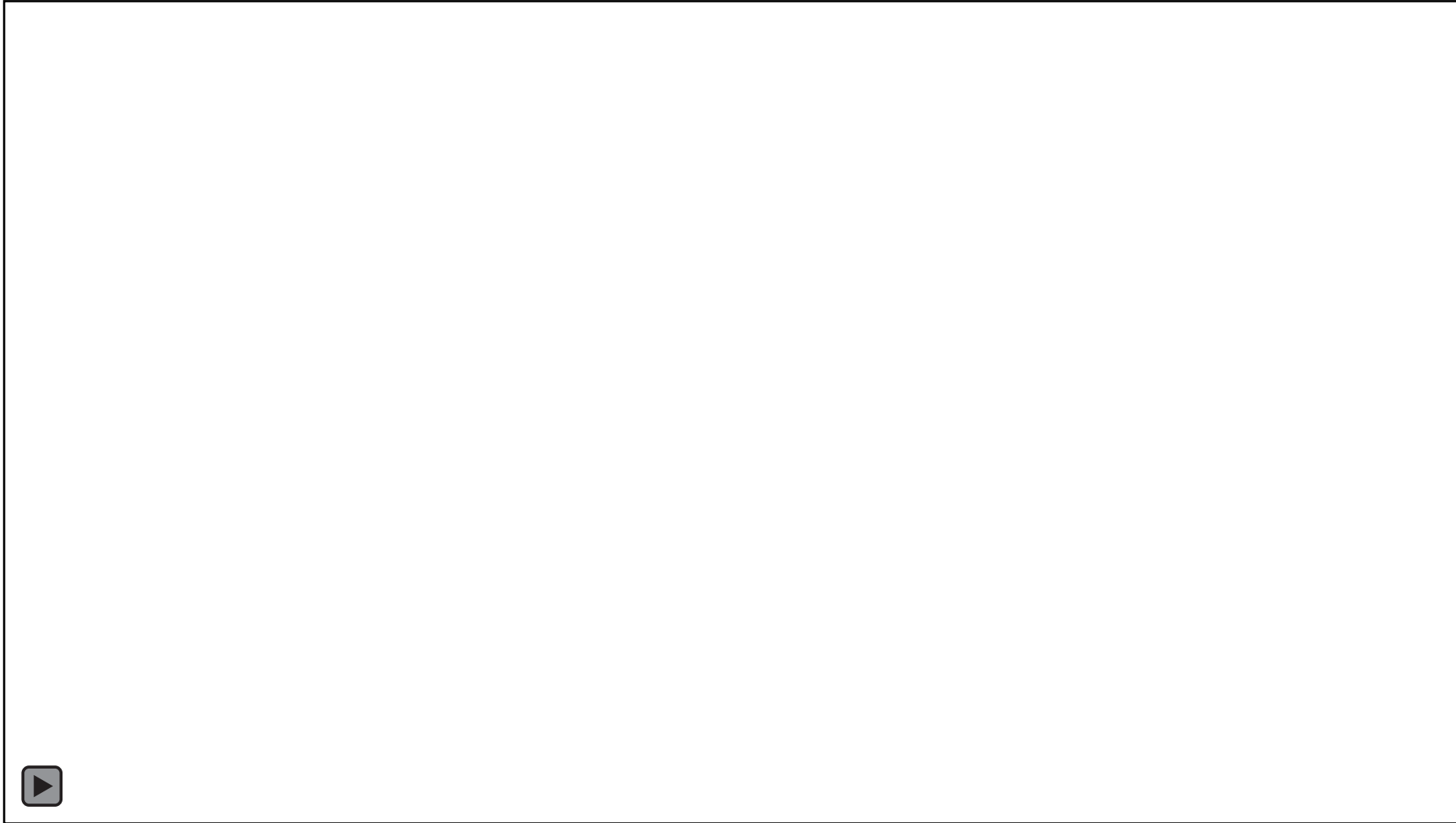
Everything under ▶ Control?

Prof. Paul M.J. Van den Hof

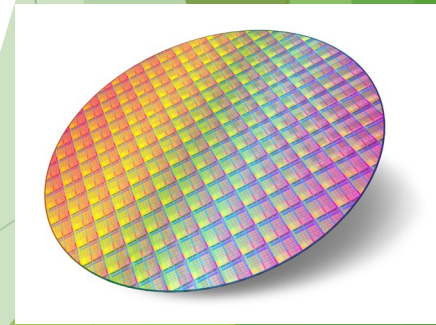
ASML lithography machine



ASML lithography machine



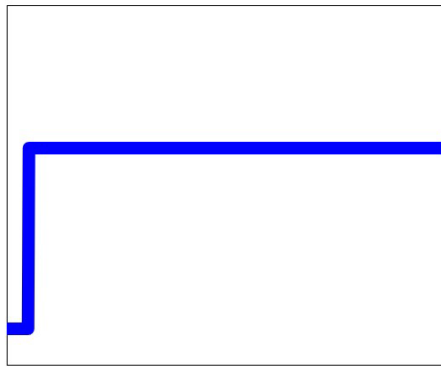

BRAINPORT
EINDHOVEN



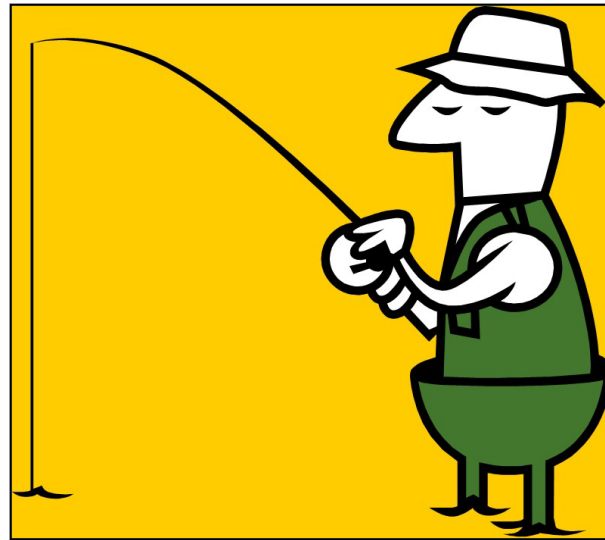
waferworld.com

What is control?

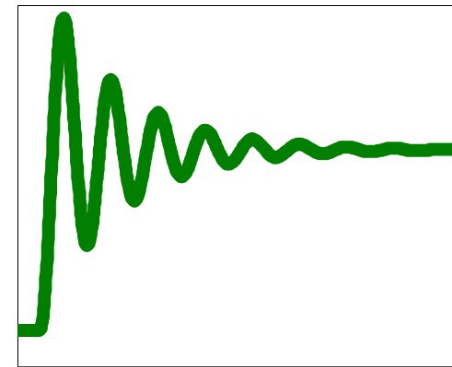
Hand position



time

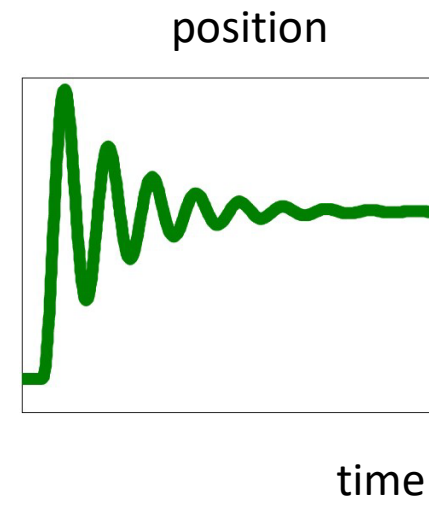
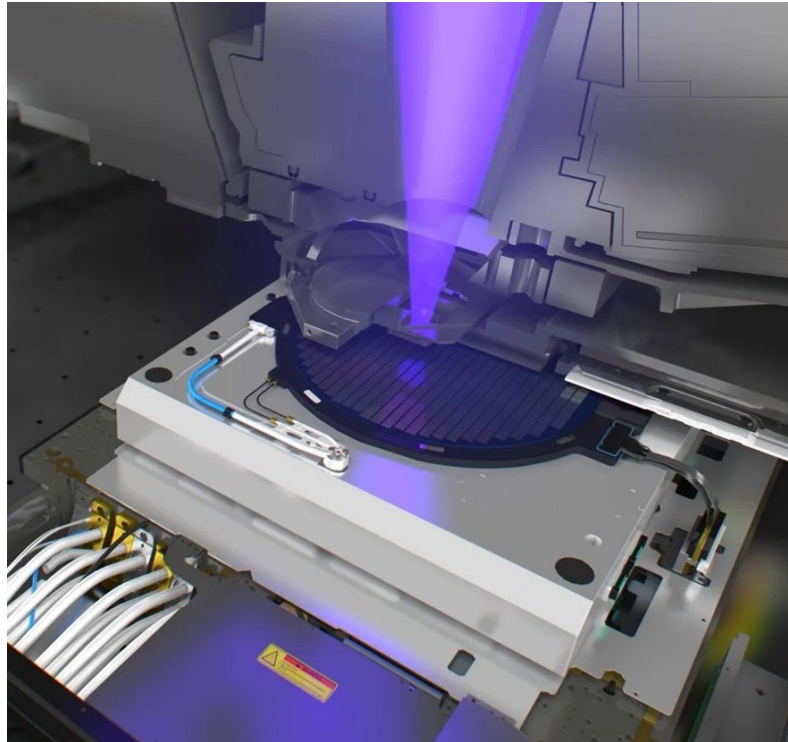
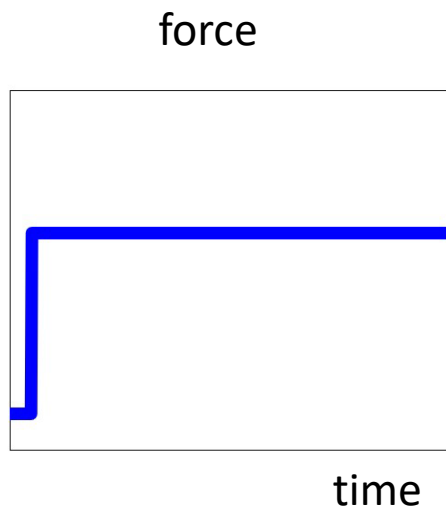


Tip position

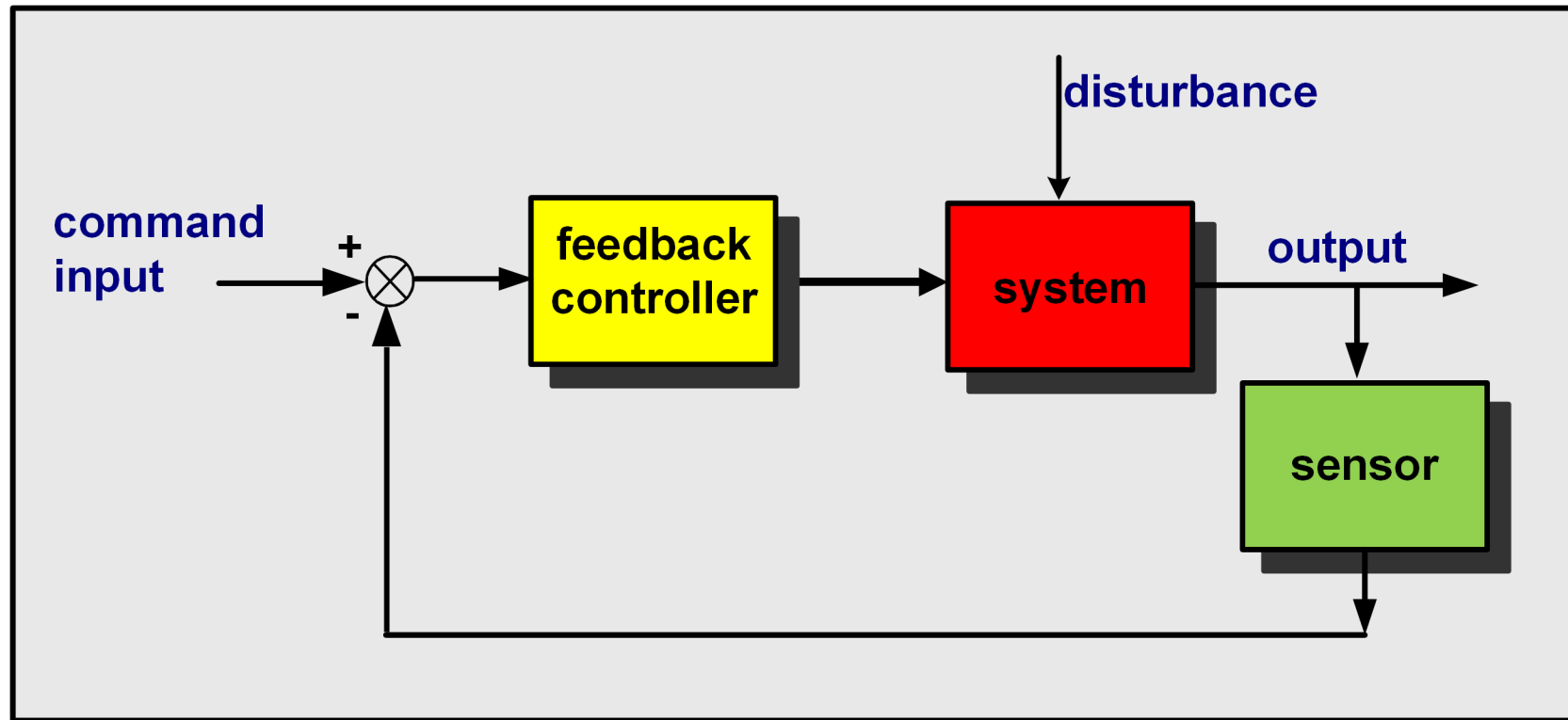


time

What is control?



What is control?

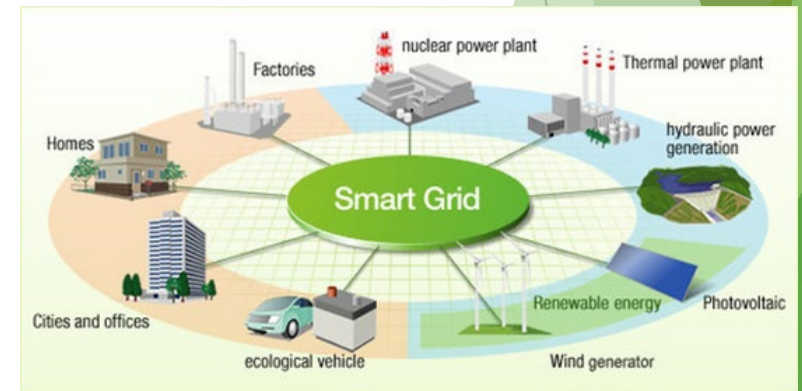


What is control?

Through feedback control, systems can be given a performance, beyond the accuracy specs of their physical components^[1]

and become robust against disturbances

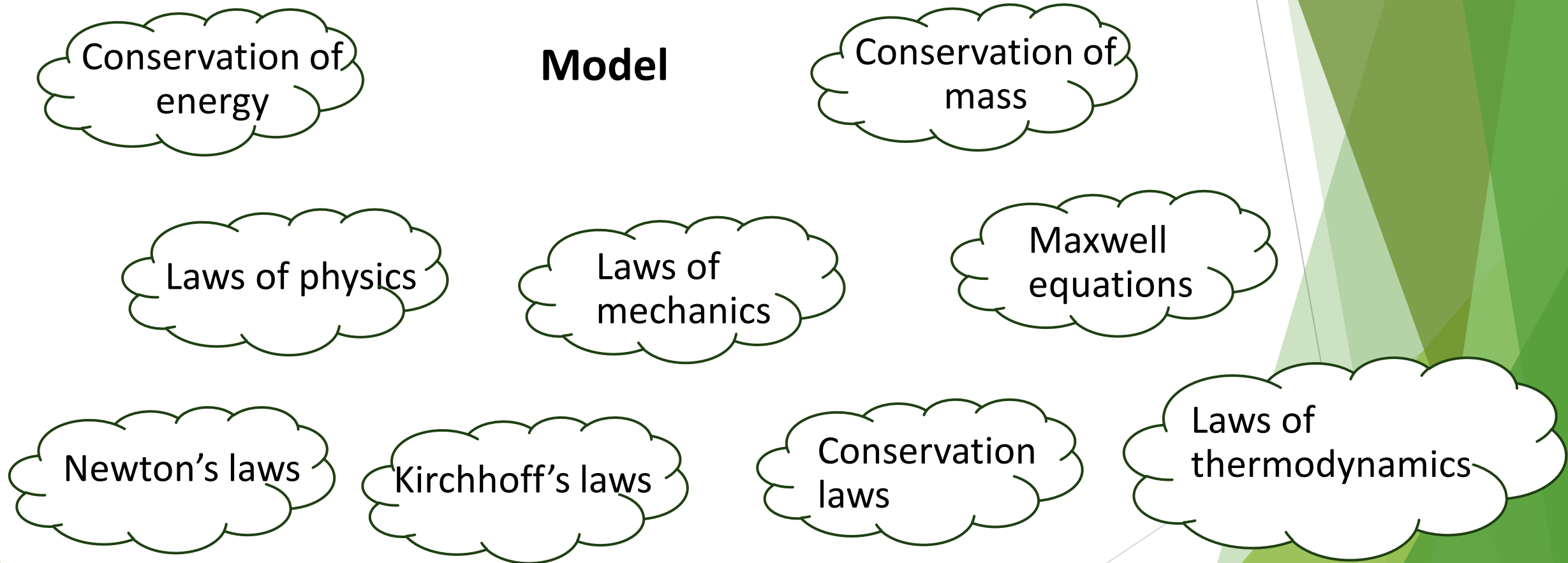
And this applies to systems in any domain of science and engineering:



[1] R.M. Murray et al., 2003.

Models

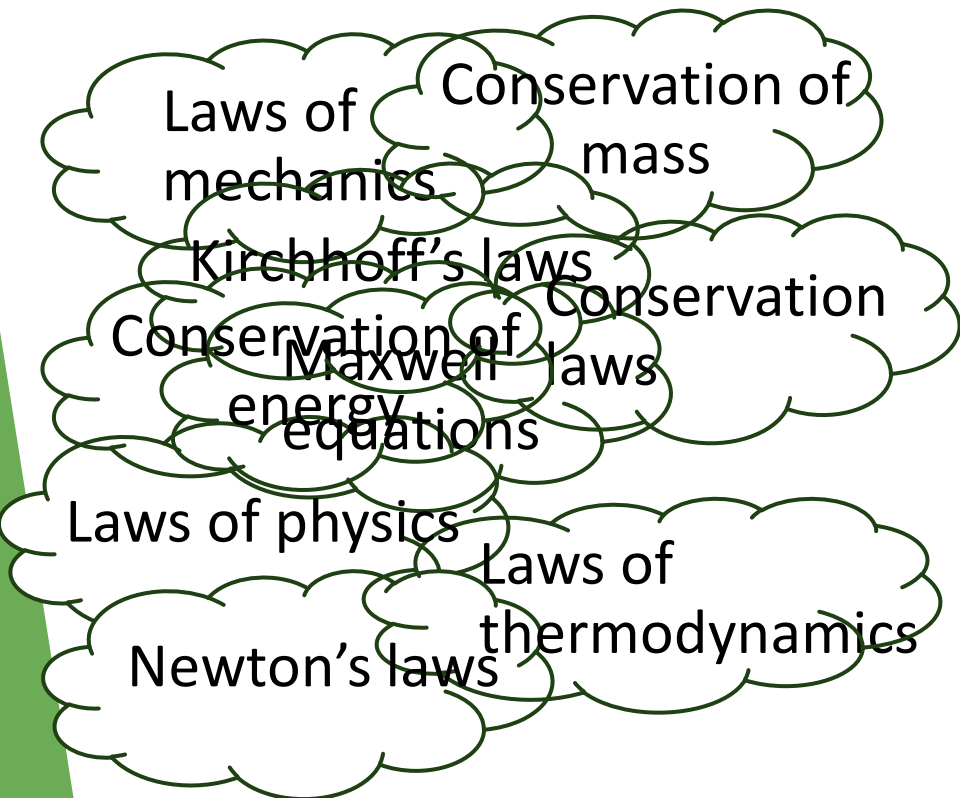
How does the system respond to inputs?



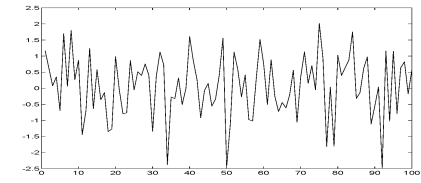
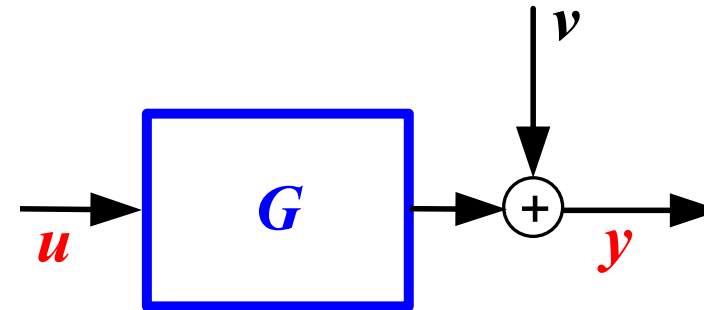
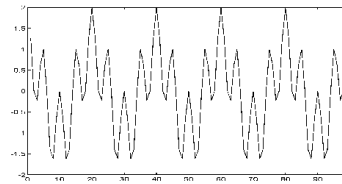
Models

How does the system respond to inputs?

Model



Data



System identification

Mathematical model

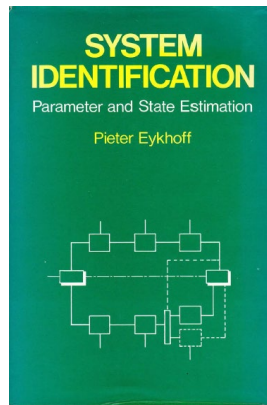
Models

How does the system respond to inputs?

Model



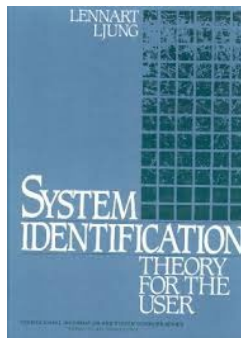
Pieter Eykhoff



1974

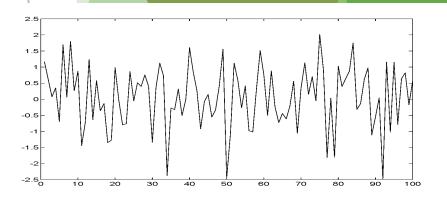
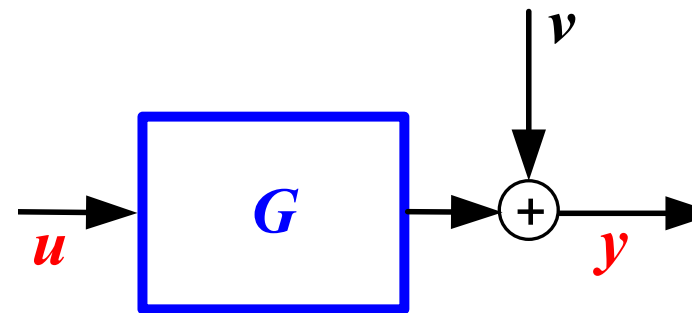
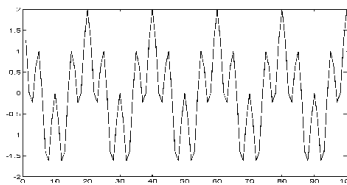


Lennart Ljung



1987

Data



Machine learning

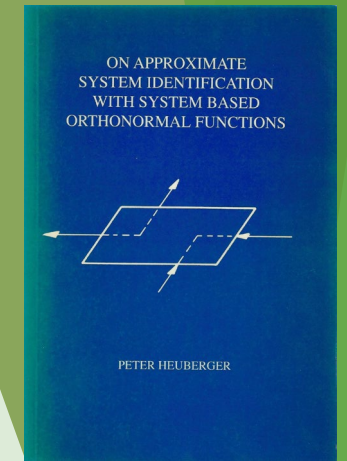
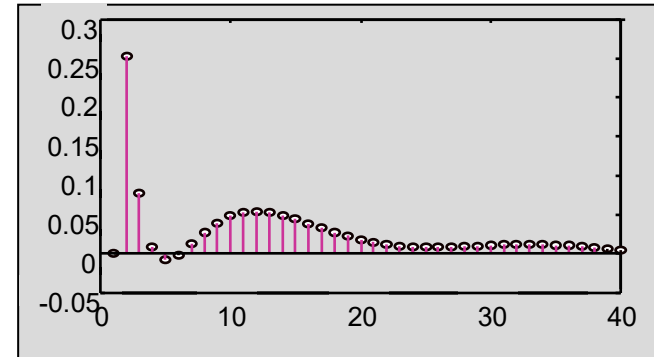
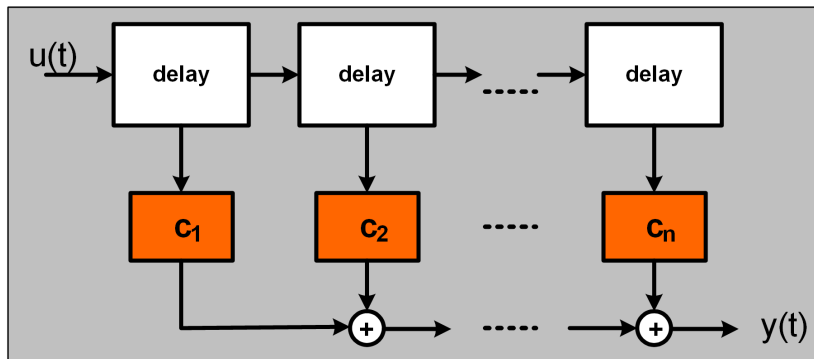
Mathematical model

The slide features a white central area with green text. The background is a dark blue/black field with a blurred line graph and data points. The graph has a white line with three points, the highest being labeled '289.33'. The background is framed by green geometric shapes on the left and right sides.

A selection of research programs

Orthogonal basis functions

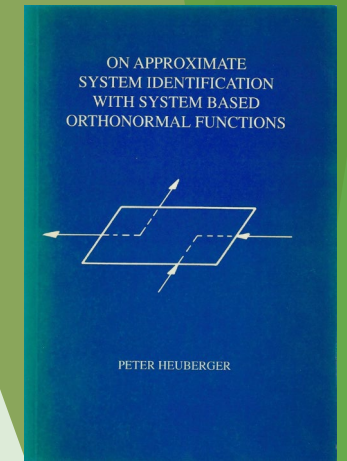
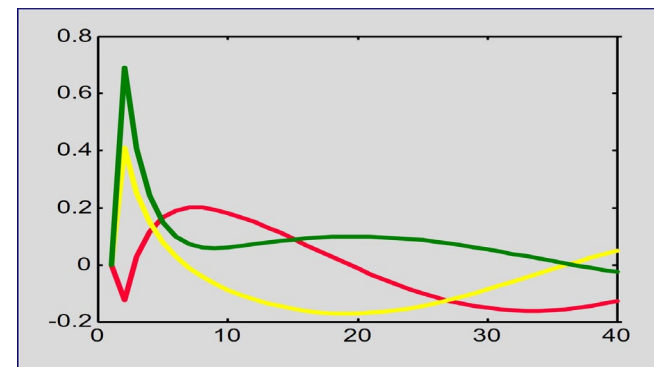
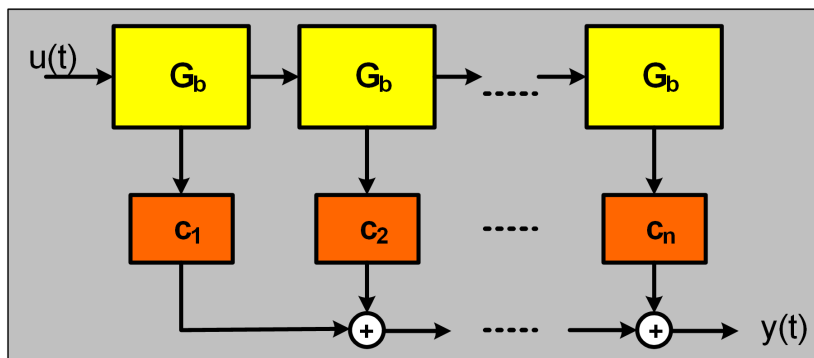
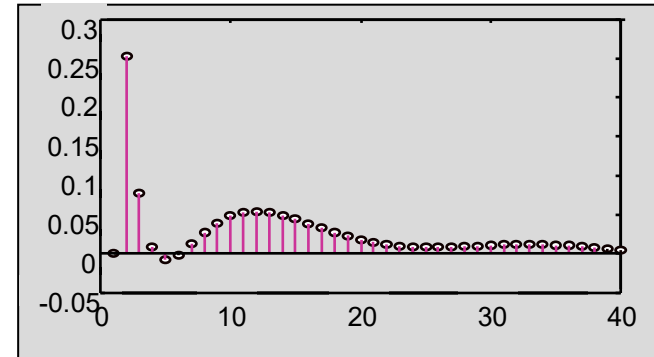
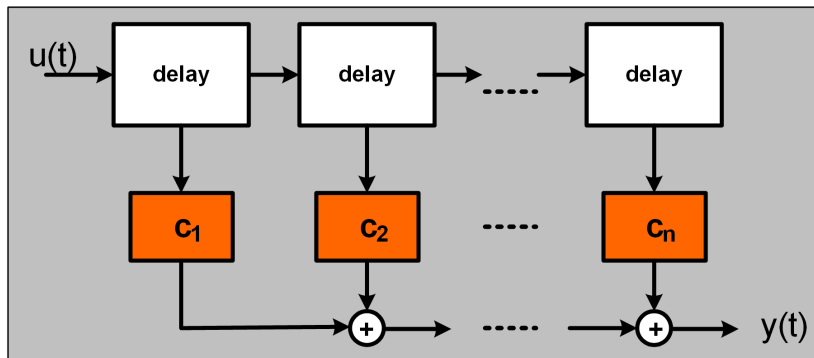
Finding an attractive model structure, to represent systems with only a small number of unknowns (parameters)



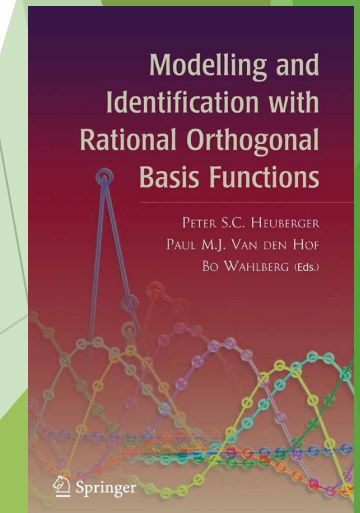
PhD Thesis
Peter Heuberger, 1991

Orthogonal basis functions

Finding an attractive model structure, to represent systems with only a small number of unknowns (parameters)

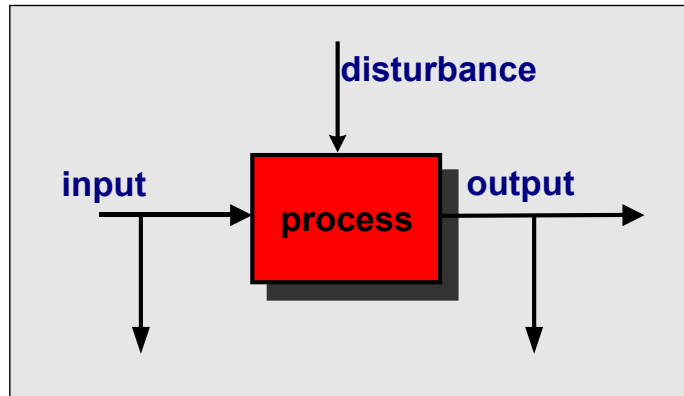


PhD Thesis
Peter Heuberger, 1991



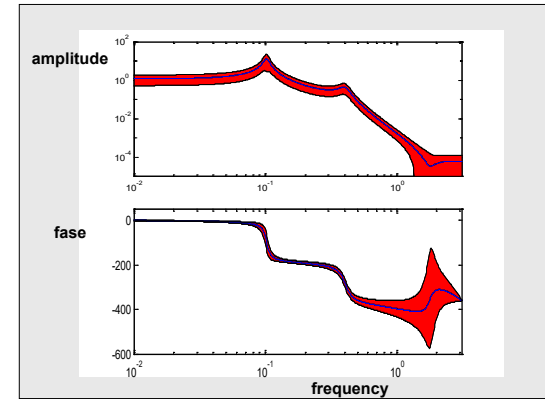
Springer, 2005

Identification for control (1990 - ...)



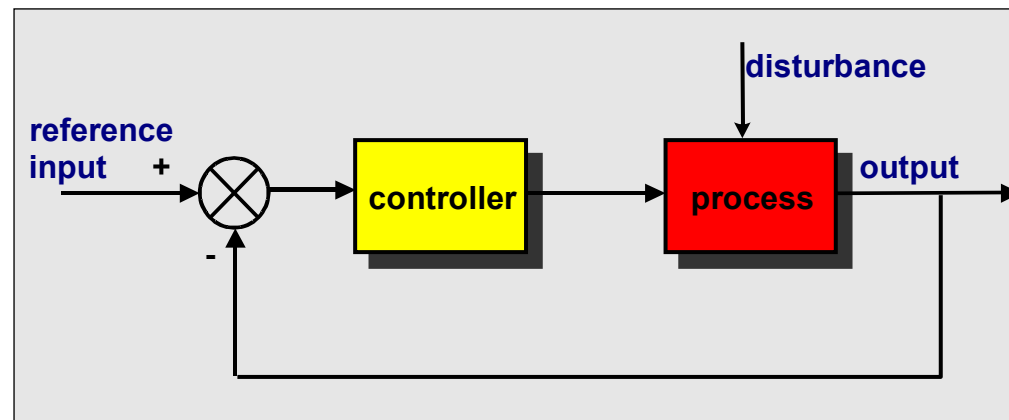
Identification

Data → Model



Feedback control system

Model → Controller

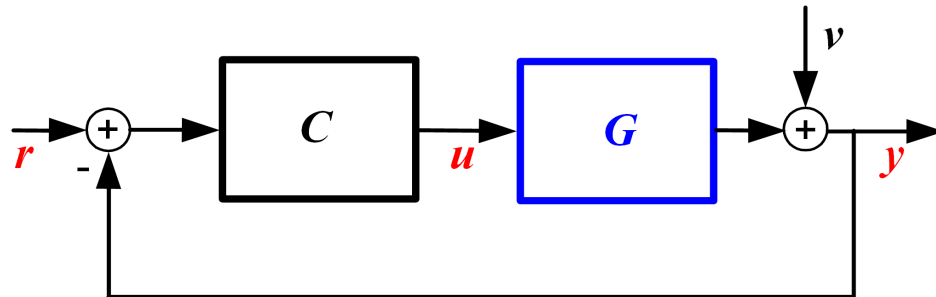


Identification for control

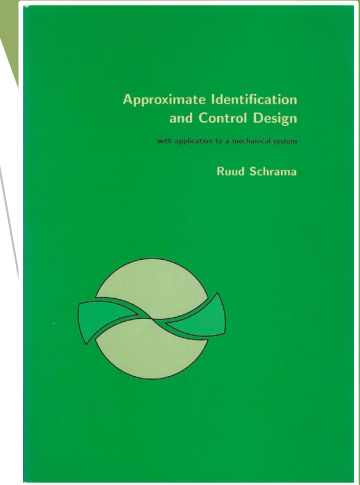
- Question:

How to identify models that are best suited for model-based control ?

- Prime result:



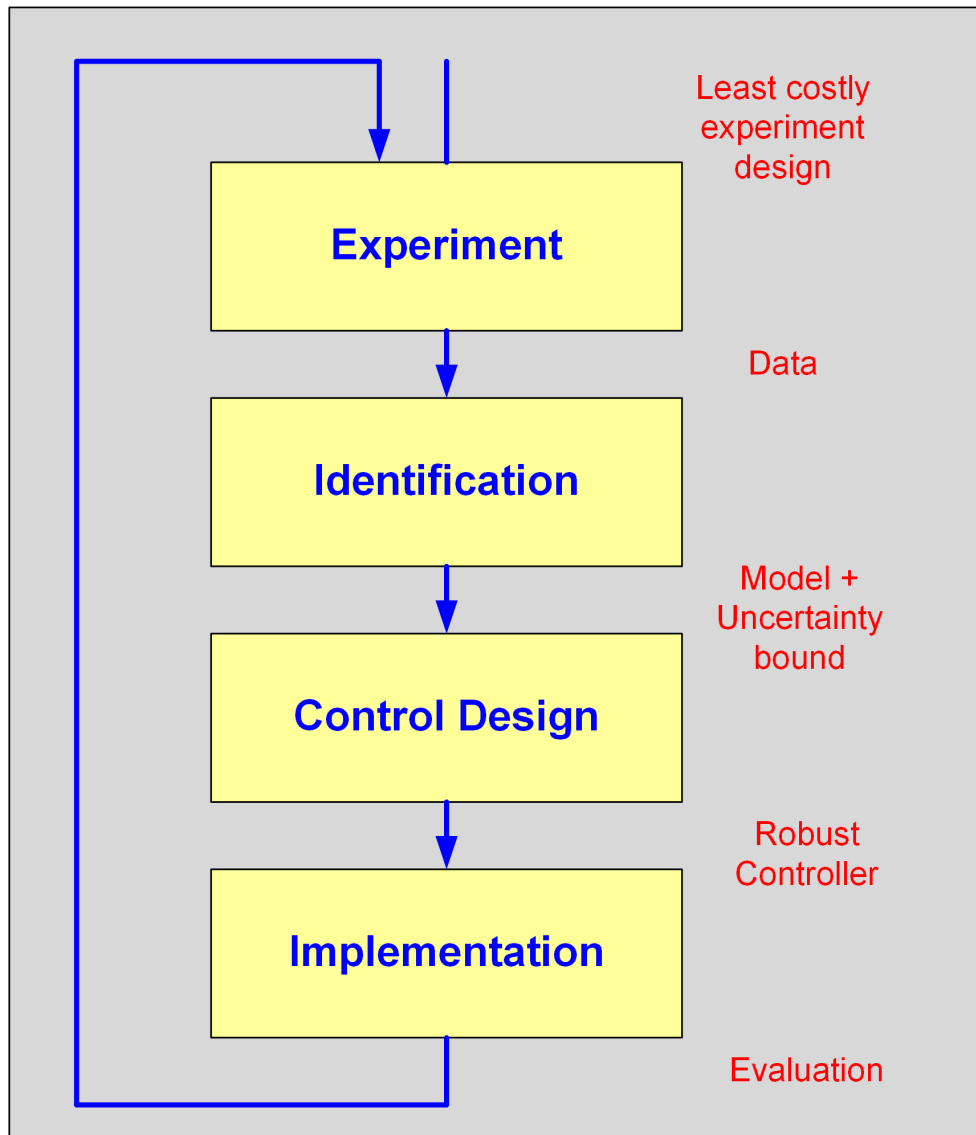
Under closed-loop control of the to-be-designed controller



Ruud Schrama
1992



Identification for control



Solution through iterative procedure

Modelling for control is **learning**

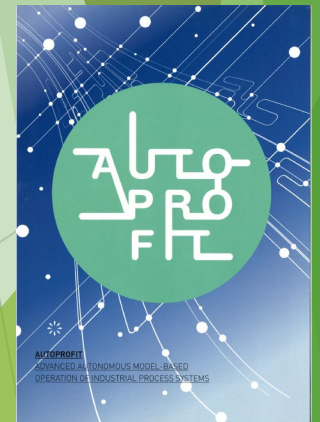
Modern version of adaptive control

Identification for control



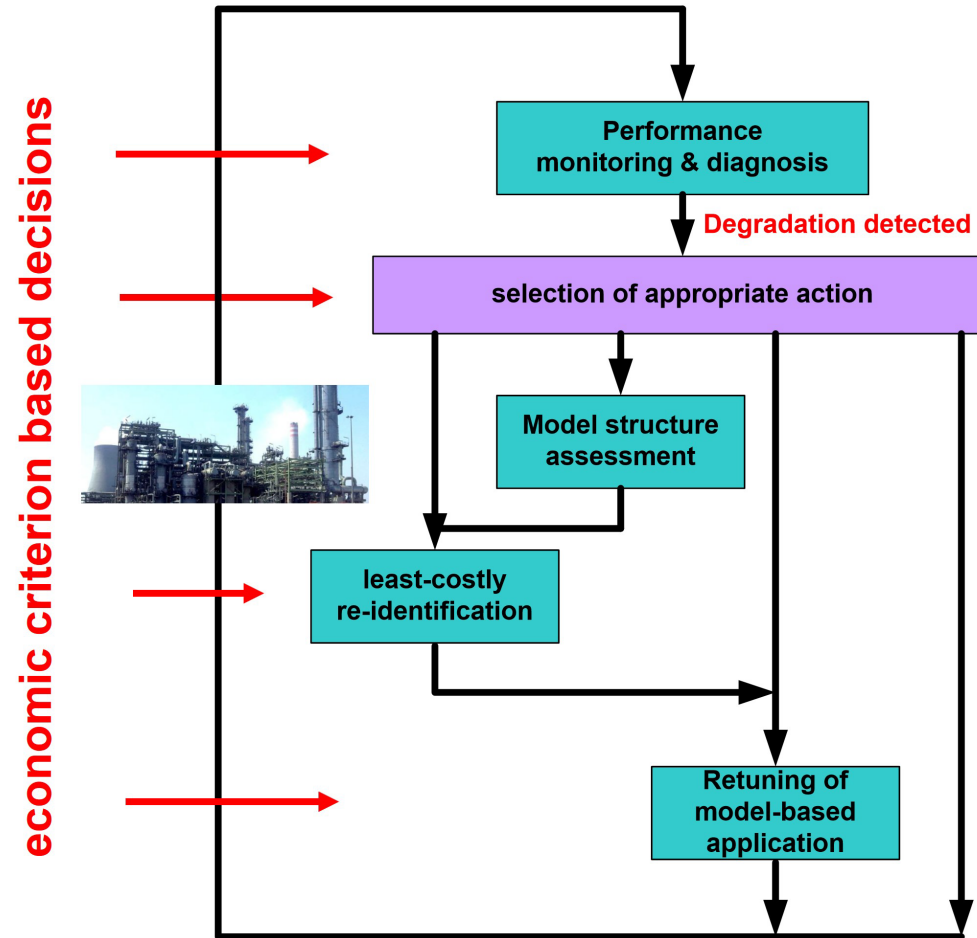
Challenge:

Bring industrial process controllers to a higher level of autonomy, through effective use of online data and model / controller updating



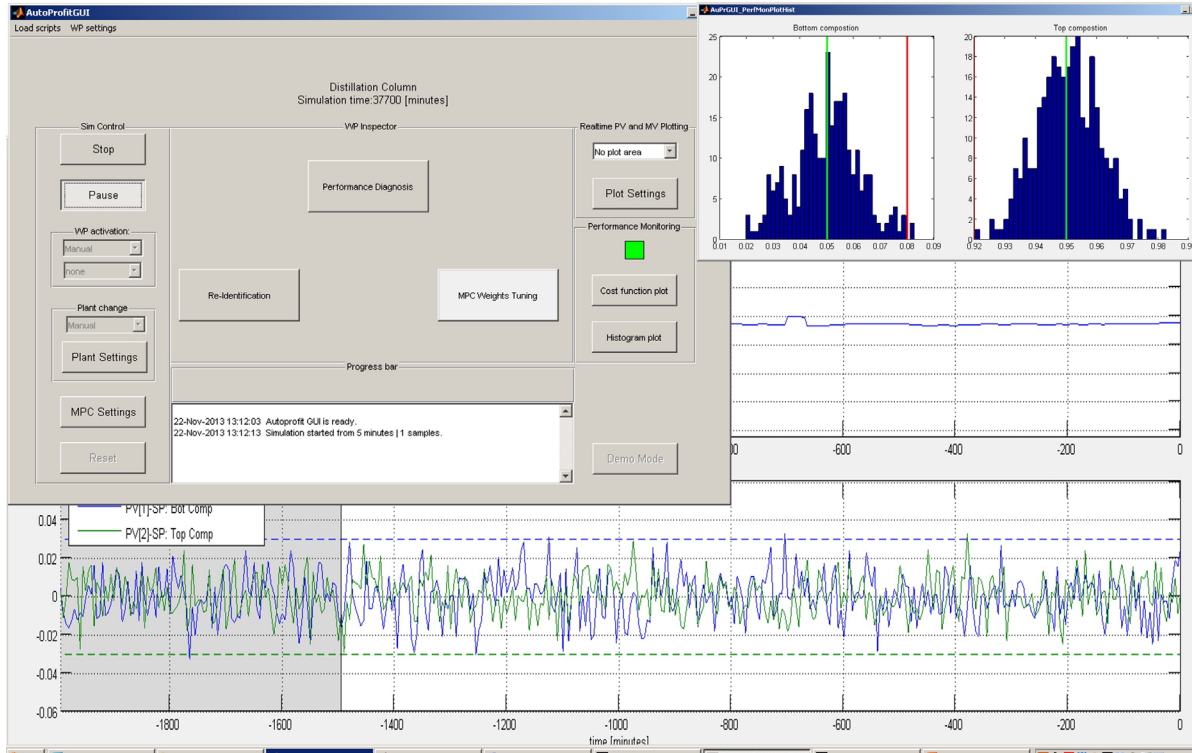
EU FP7 STREP 2010-2013

Identification for control



Autonomous maintenance loop for linear model-based operation

Identification for control



Sasol site Secunda,
South Africa

Identification for control

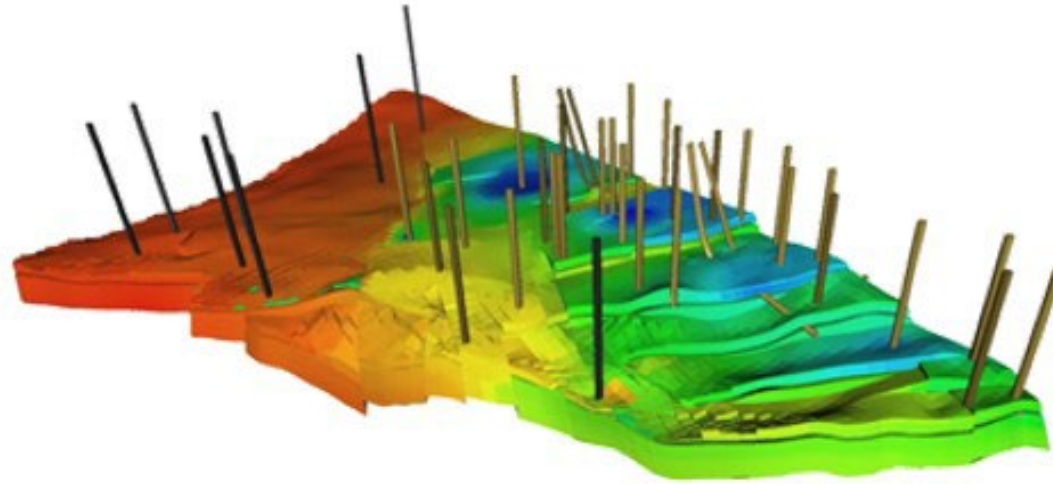


No continuation after 2014

Reservoir Engineering (2002-2018)

Joint effort:

- TUD Systems & Control
- TUD Applied Earth Sciences
- Shell

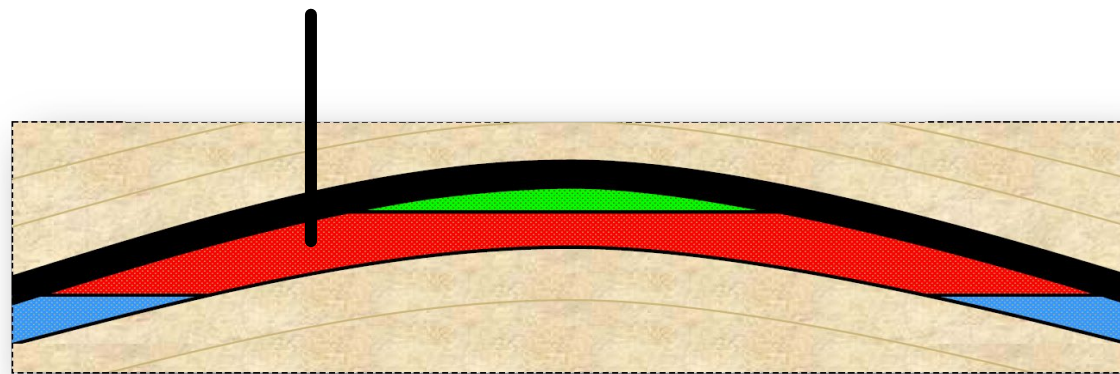


THE VALUE OF SMARTNESS



Oil Production

- Porous rock with oil in pores
- 1 – 10 km underground

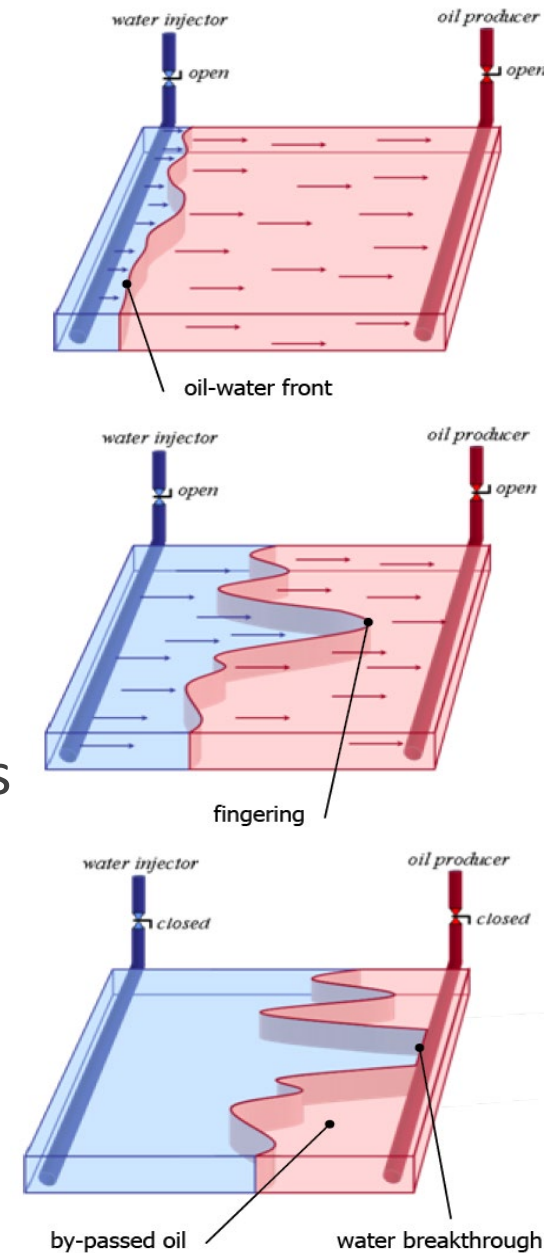


side view

- cap rock
- water bearing reservoir rock
- non- reservoir rock
- oil bearing reservoir rock
- gas bearing reservoir rock

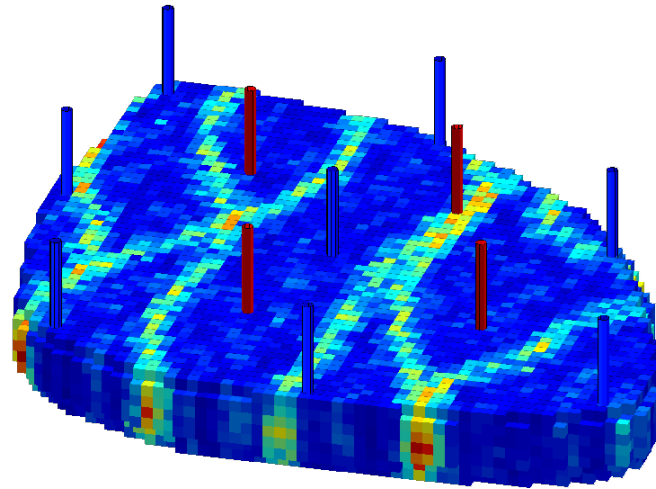
Oil Production

- **Waterflooding** (WF) popular secondary recovery process
- Smart wells have sensors and control valves
- Life time of reservoir in the order of decades
- Lack of smart operational strategy

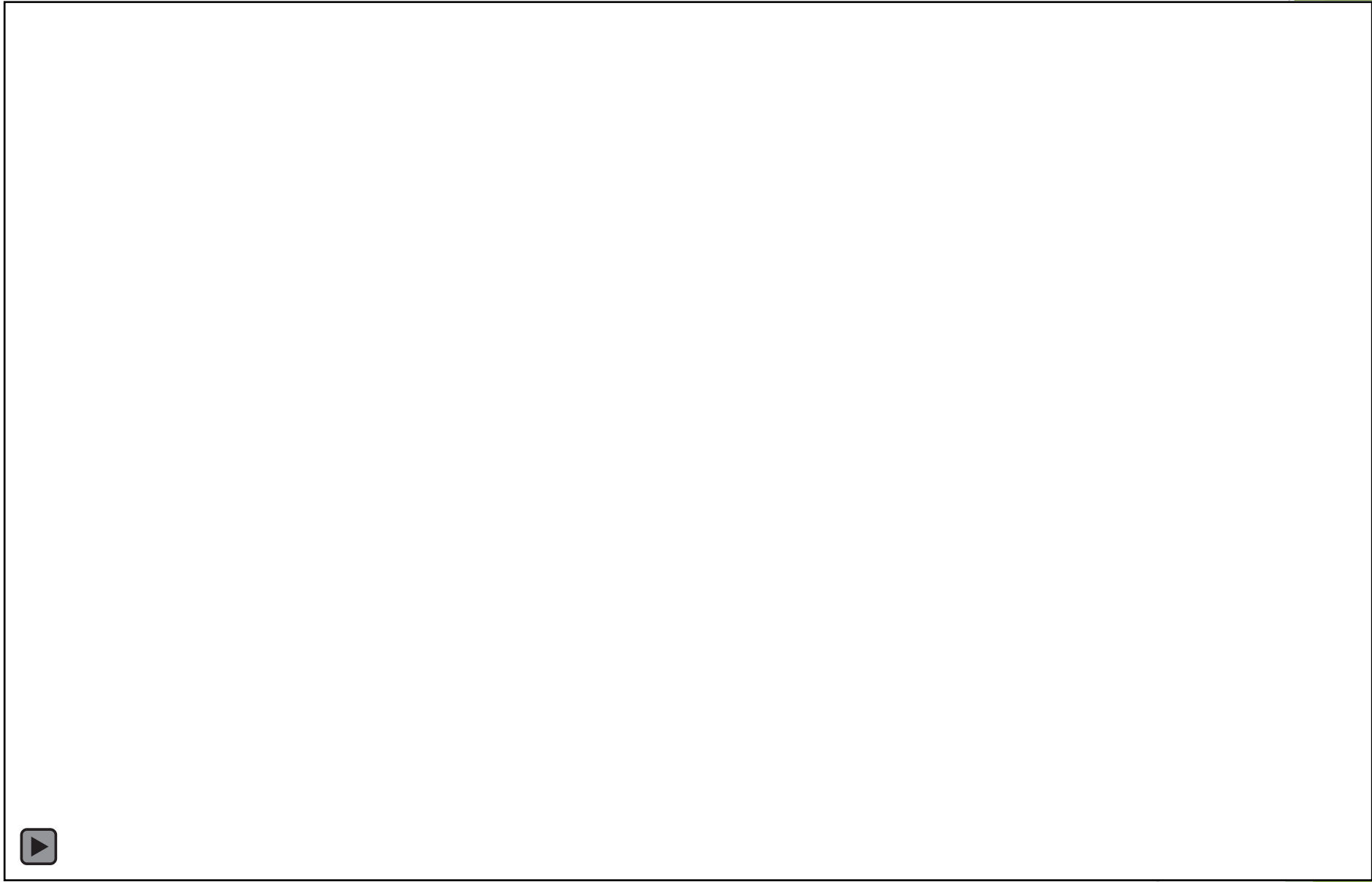


Reservoir characteristics

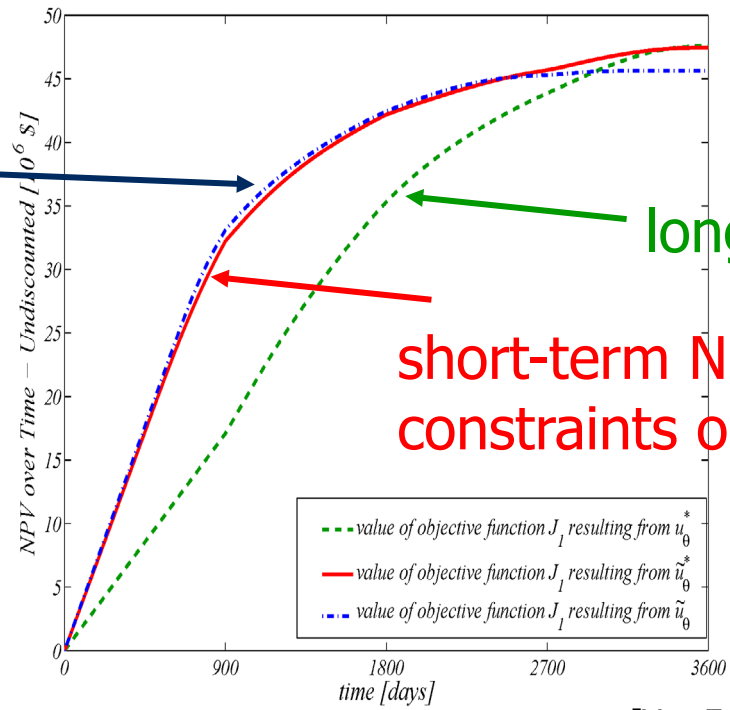
- heterogeneity of reservoir
- flow dynamics determined by geological structure (permeability)



(Gijs van Essen et al., CAA 2006)



reactive



long term NPV

short-term NPV under constraints on long-term NPV

[Van Essen et al, SPE J, 2011]
IFAC 2012

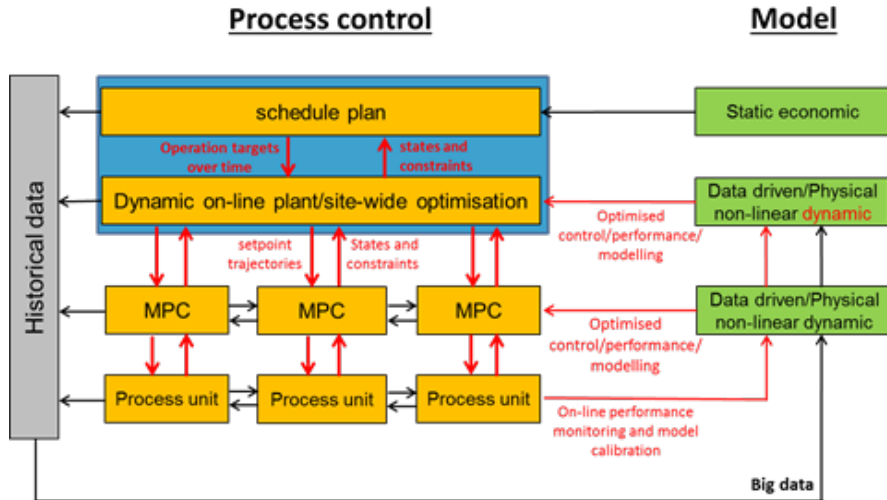
- Decision making under geological and economic uncertainty
- Online improvement of geological models



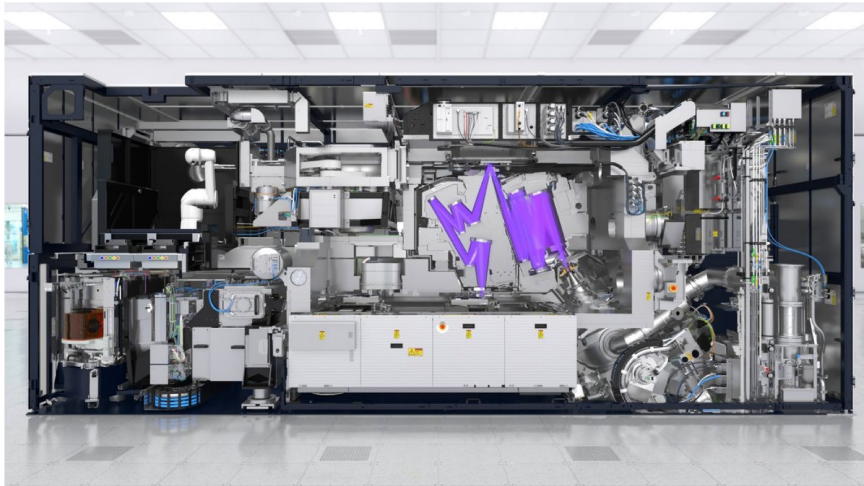
Identification in dynamic networks



Decentralized process control



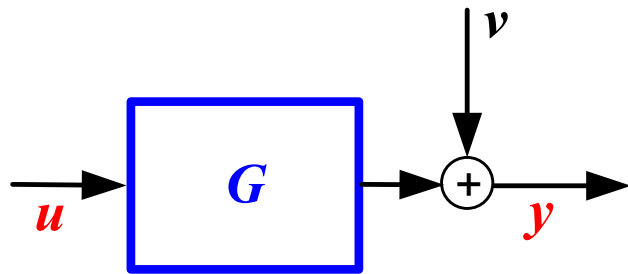
Complex machines



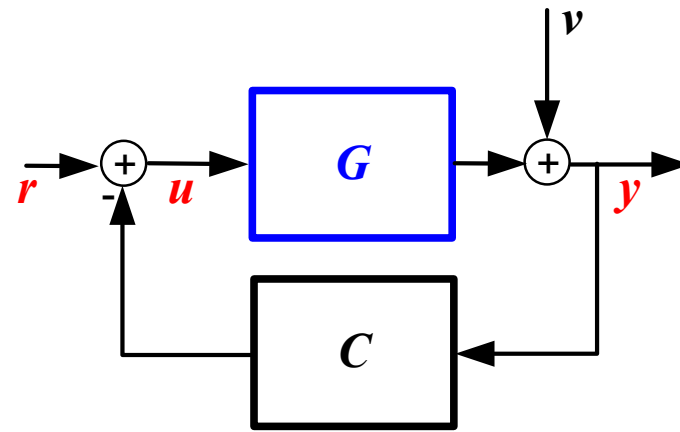
- (Large-scale) interconnected dynamic systems
- Data is “everywhere”, AI/machine learning tools
- Learning models from data

Identification in dynamic networks

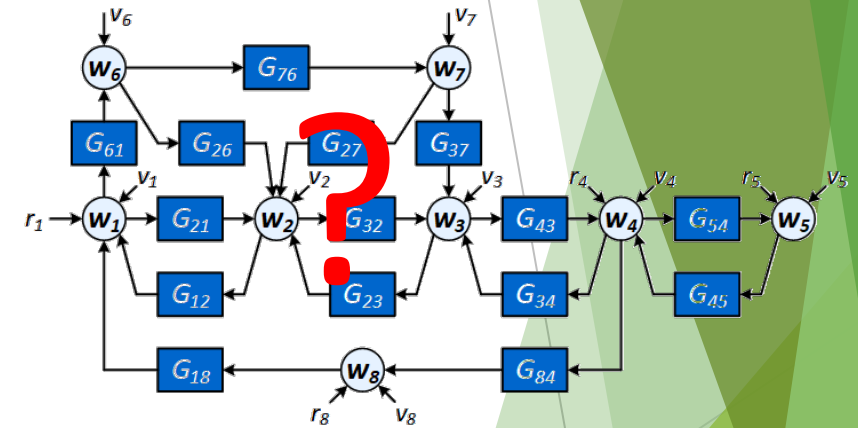
Open-loop



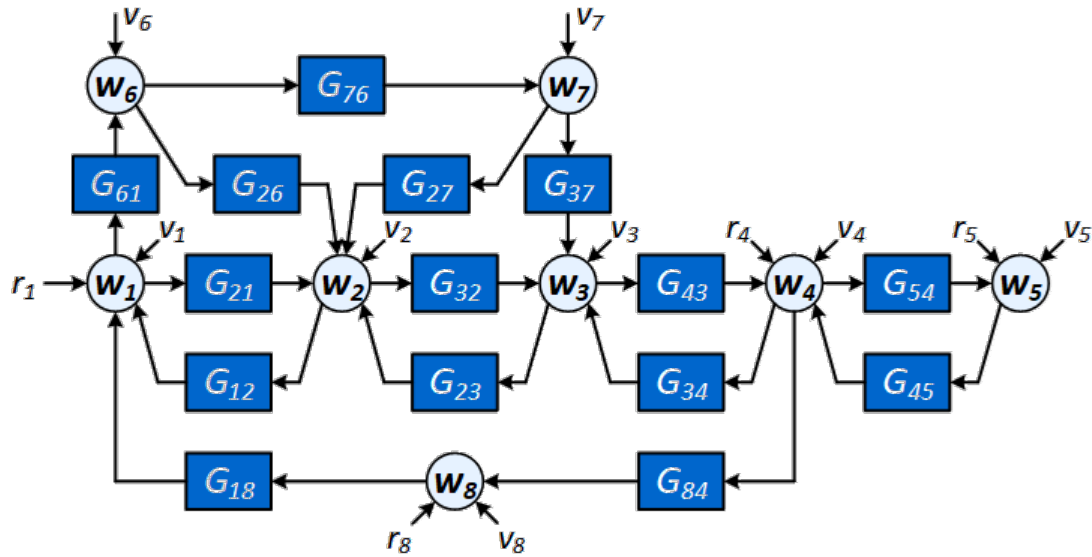
Closed-loop



Networks



Identification in dynamic networks

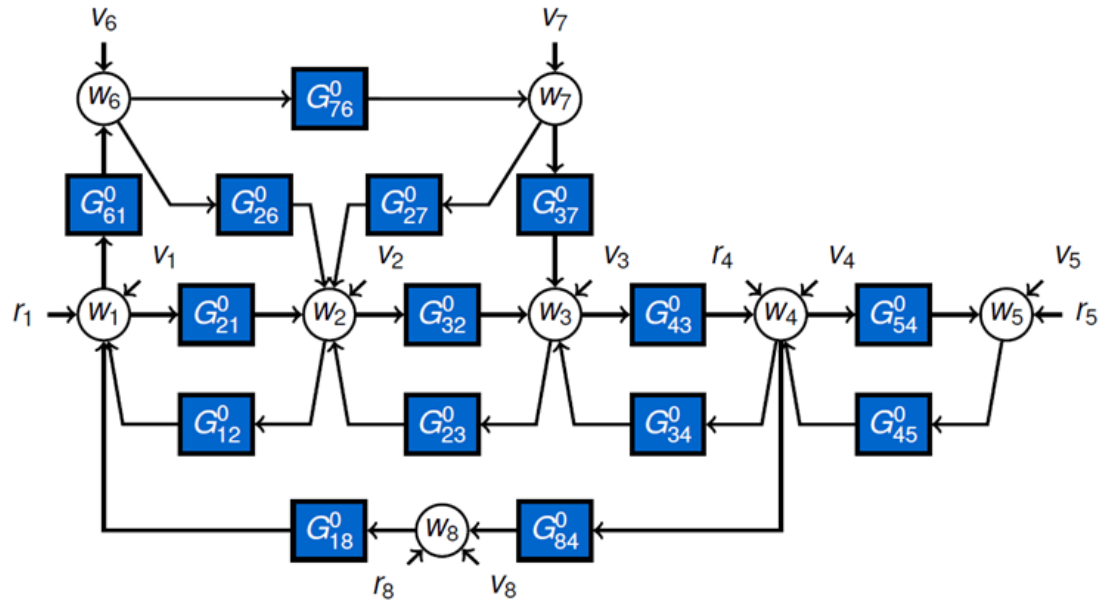


- Introducing structure/topology
- Developing the fundamental theory

**SYSTEM ID
ENTIFICATI
ON IN DYNA
MIC NETW
ORKS** ARNE
DANKERS

(2014)

Identification in dynamic networks

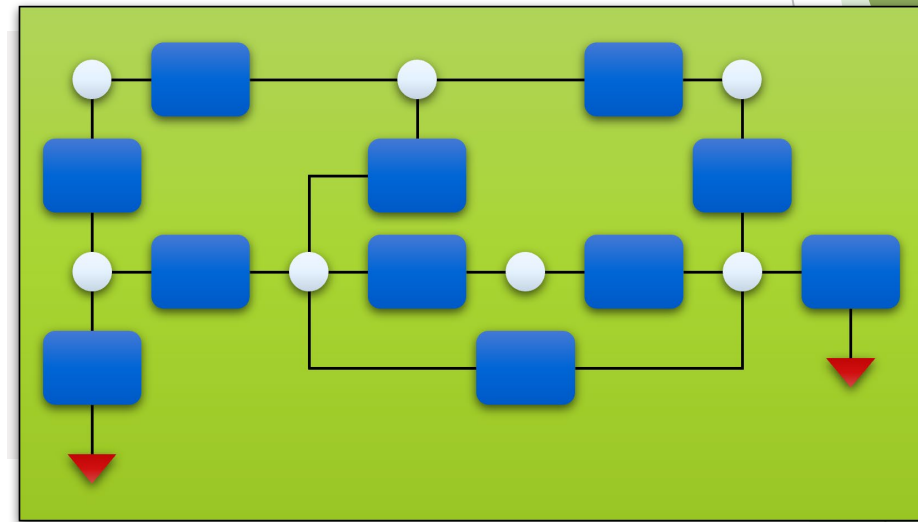
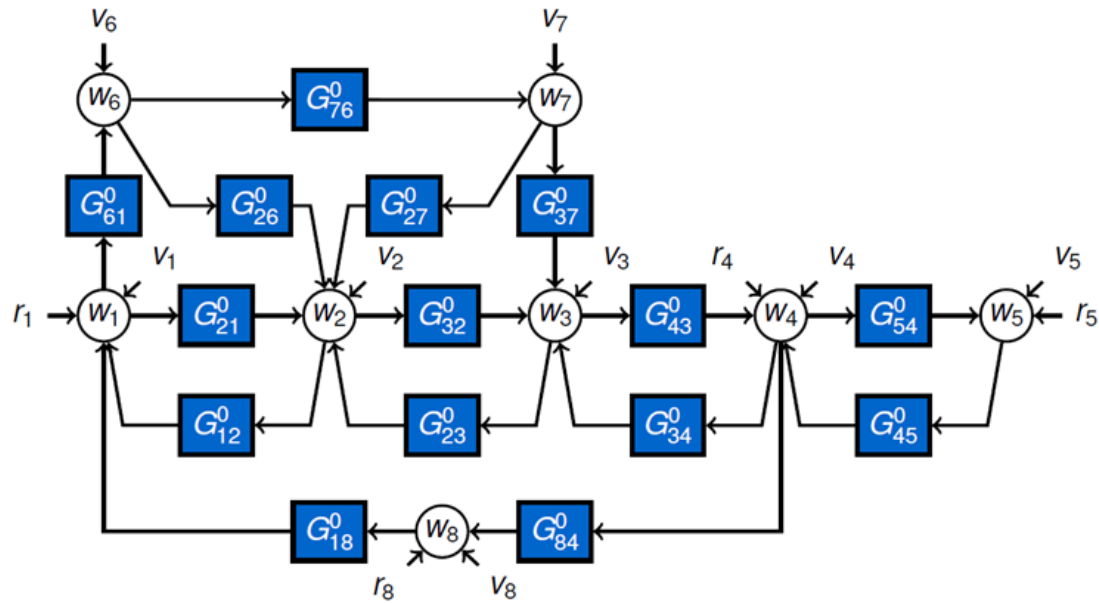


Many open problems

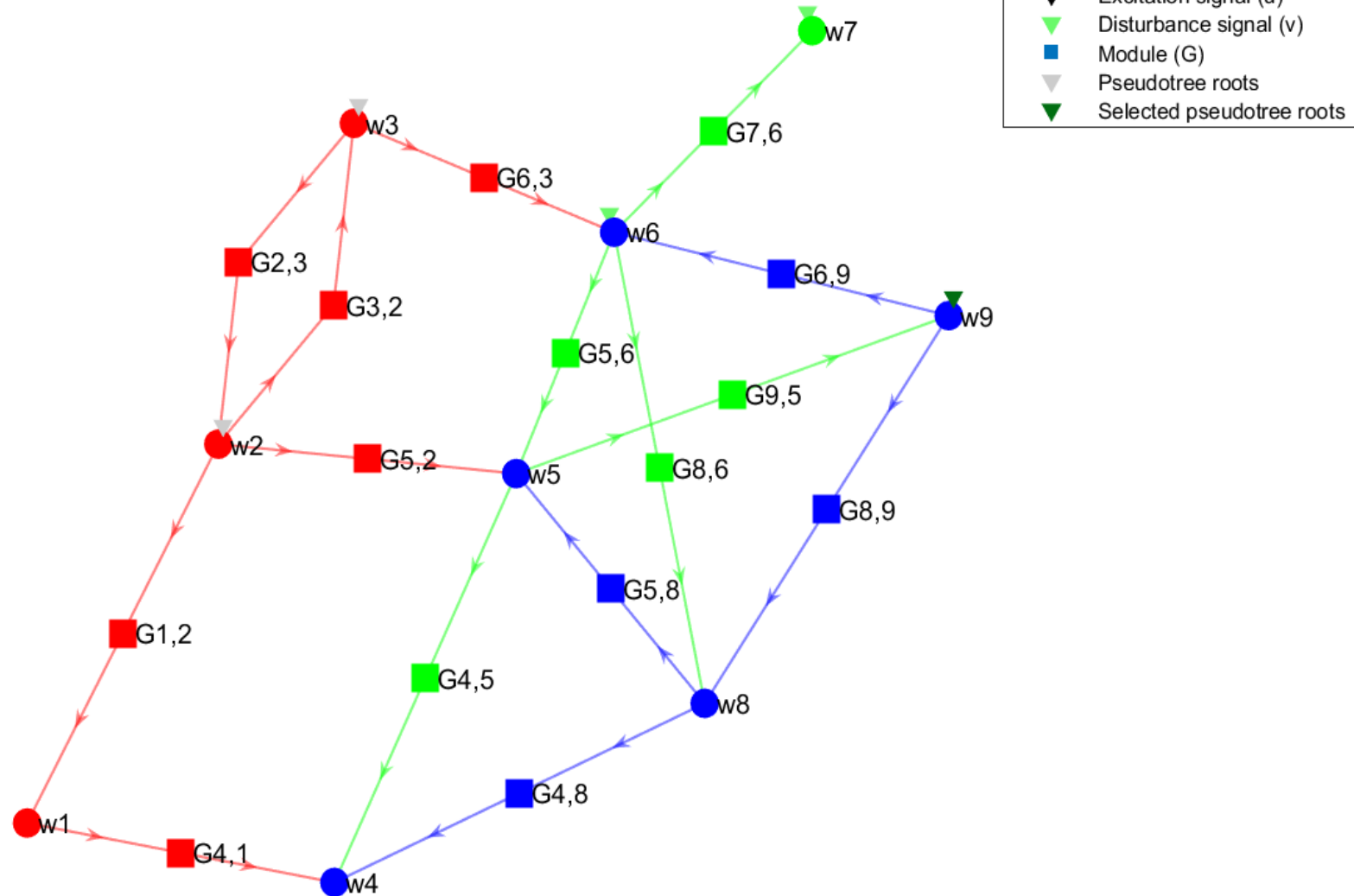


European Research Council

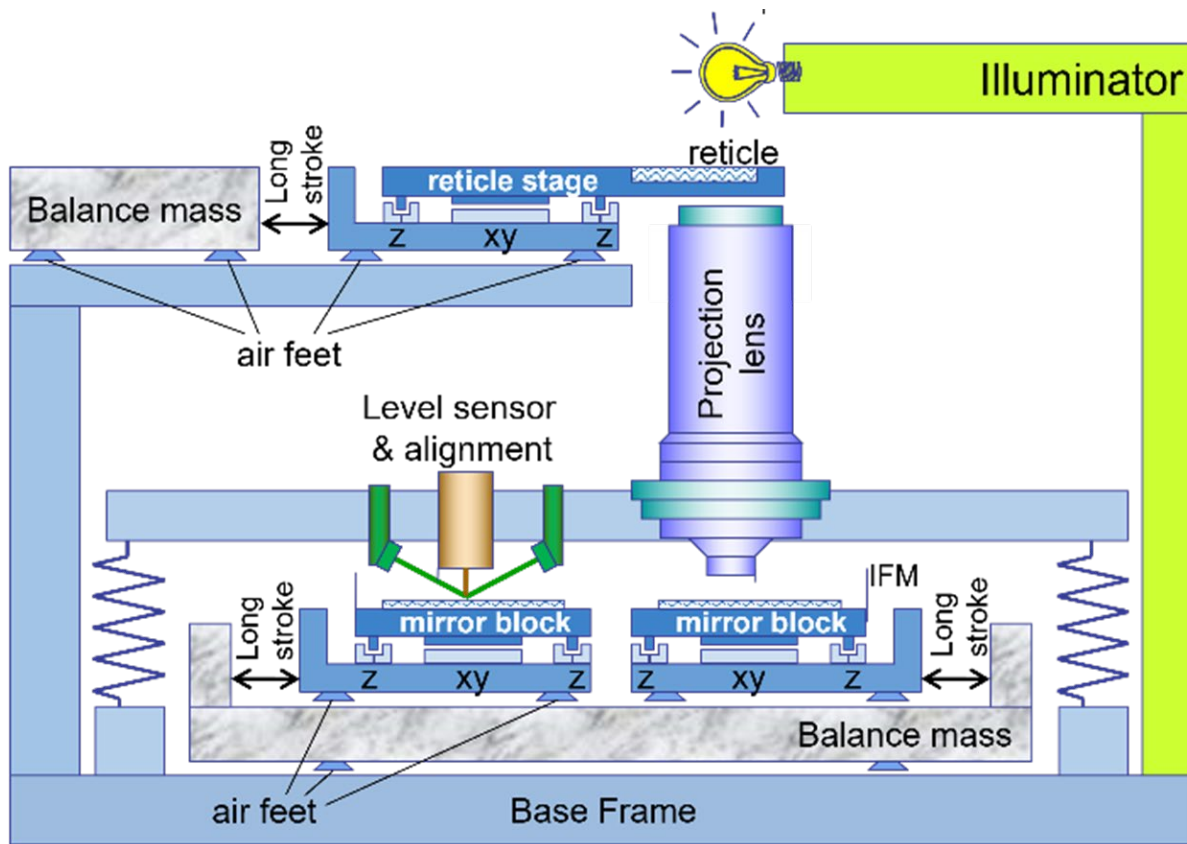
Identification in dynamic networks



Identification in dynamic networks



Diagnostics in lithography systems



- Many interconnected subsystems
- Need for very fast recovery from faults
- Tools for automated diagnostics

SYSDYNET MATLAB App and Toolbox

TU/e Dynamic Network App

File Actions View Highlight Edit Operations Identifiability Predictor Model Help

Dynamic Network: Editor TU/e Eindhoven University of Technology

Edit

Nodes

Action: Add Delete

Type: External excit... ▼

From: Select ▼

To: Select ▼

Add

Links

Action: Add Delete

From: Select ▼

To: Select ▼

Connect Clear

Properties

node	measured
w1	<input checked="" type="checkbox"/>
w2	<input type="checkbox"/>
w3	<input type="checkbox"/>
w4	<input checked="" type="checkbox"/>
w5	<input checked="" type="checkbox"/>
w6	<input checked="" type="checkbox"/>
w7	<input checked="" type="checkbox"/>

Modules

Single Module
 All Modules

Select ▼


Known
 Switching
 Strictly Proper

Network

- Node (w)
- External excitation (r)
- White noise (e)
- Module (G)

erc
European Research Council

www.sysdynet.net



Researcher,
supervisor,
teacher and
manager



A fantastic
job in an
international
setting

International setting





It's all about
people

PhD students



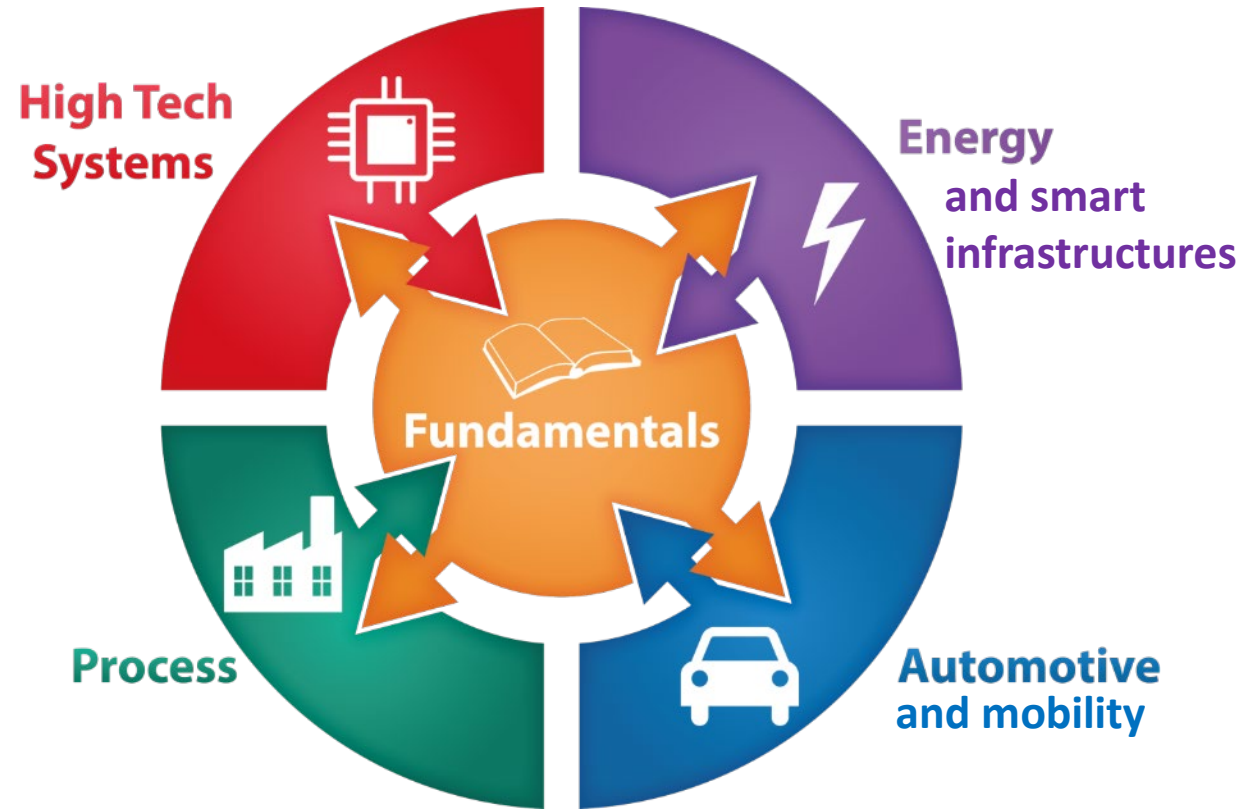
The PhD students



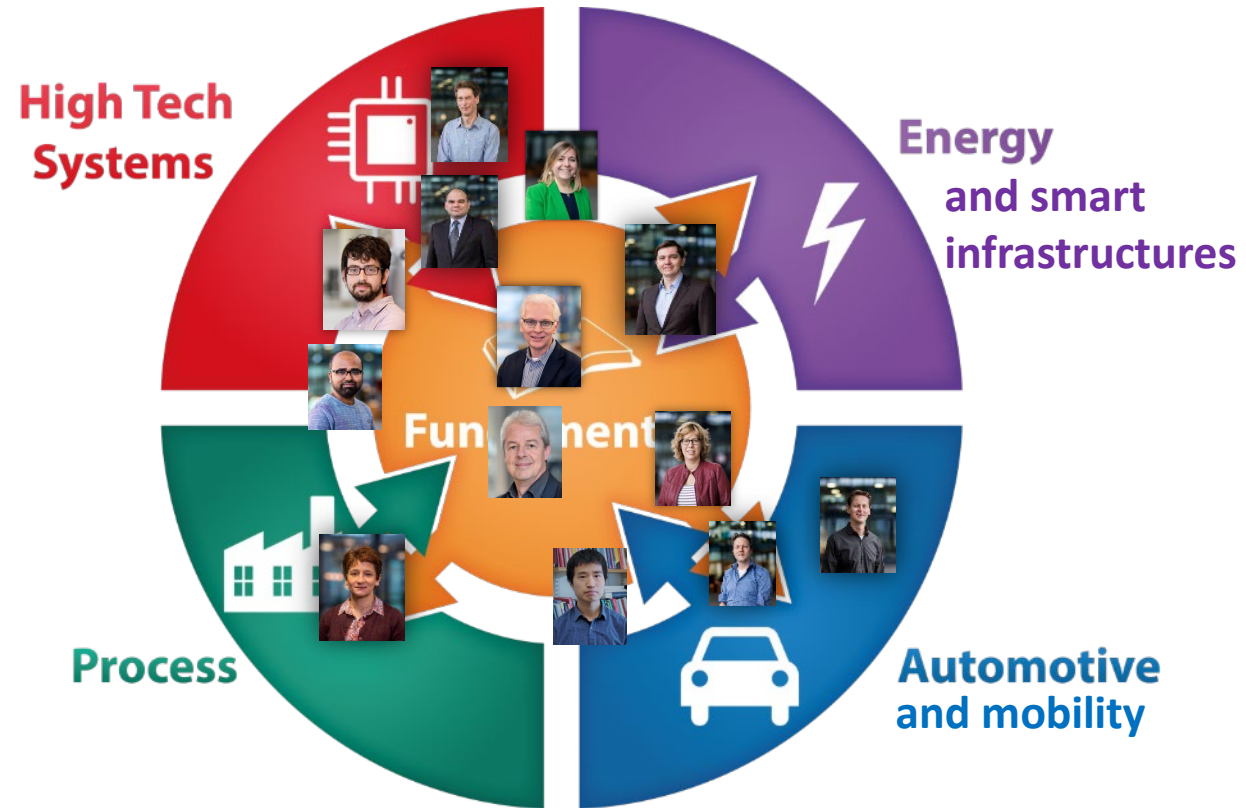
Building a team



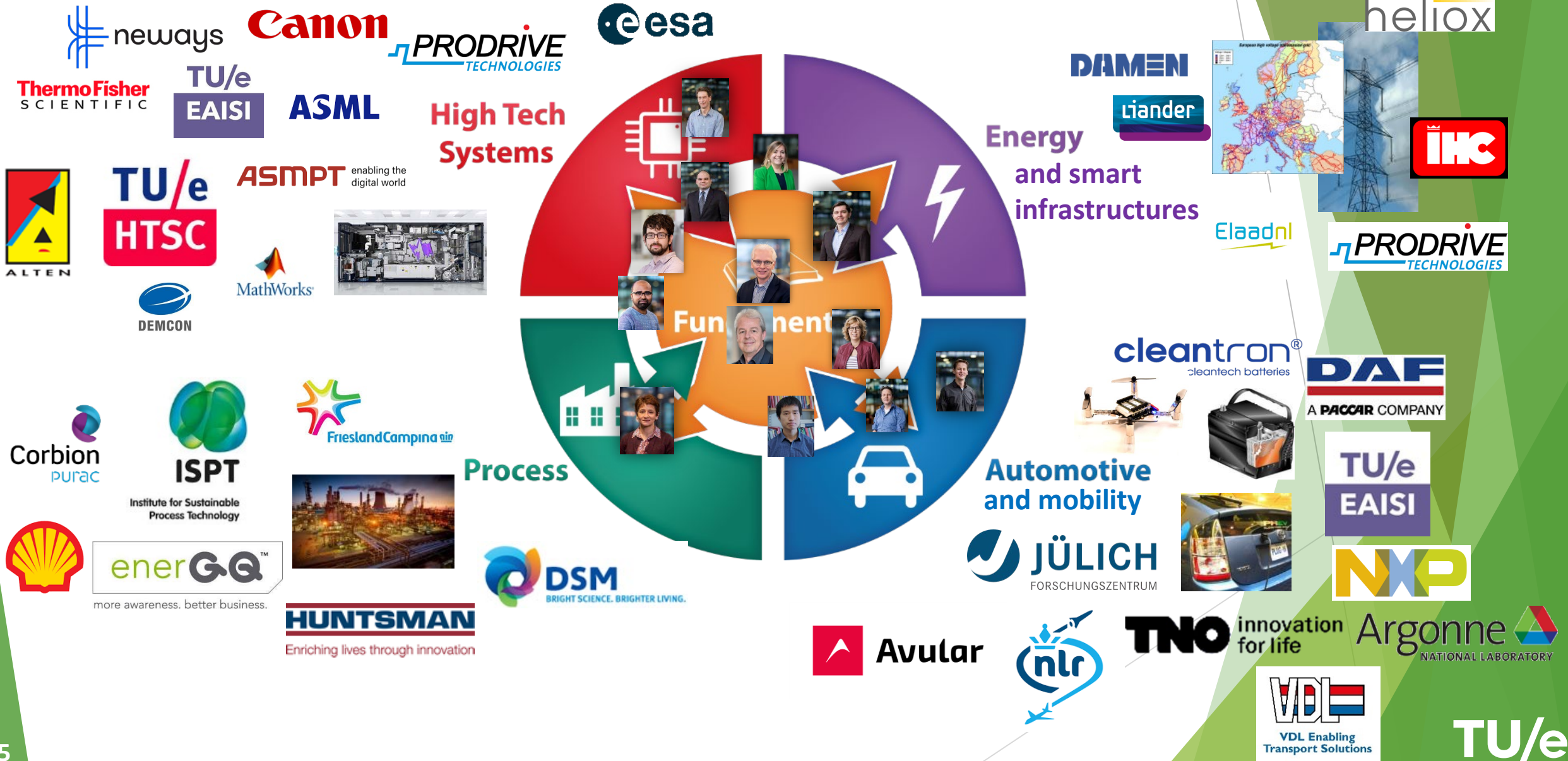
Research domains – Control Systems Group



Research domains – Control Systems Group



Research domains – Control Systems Group



National setting

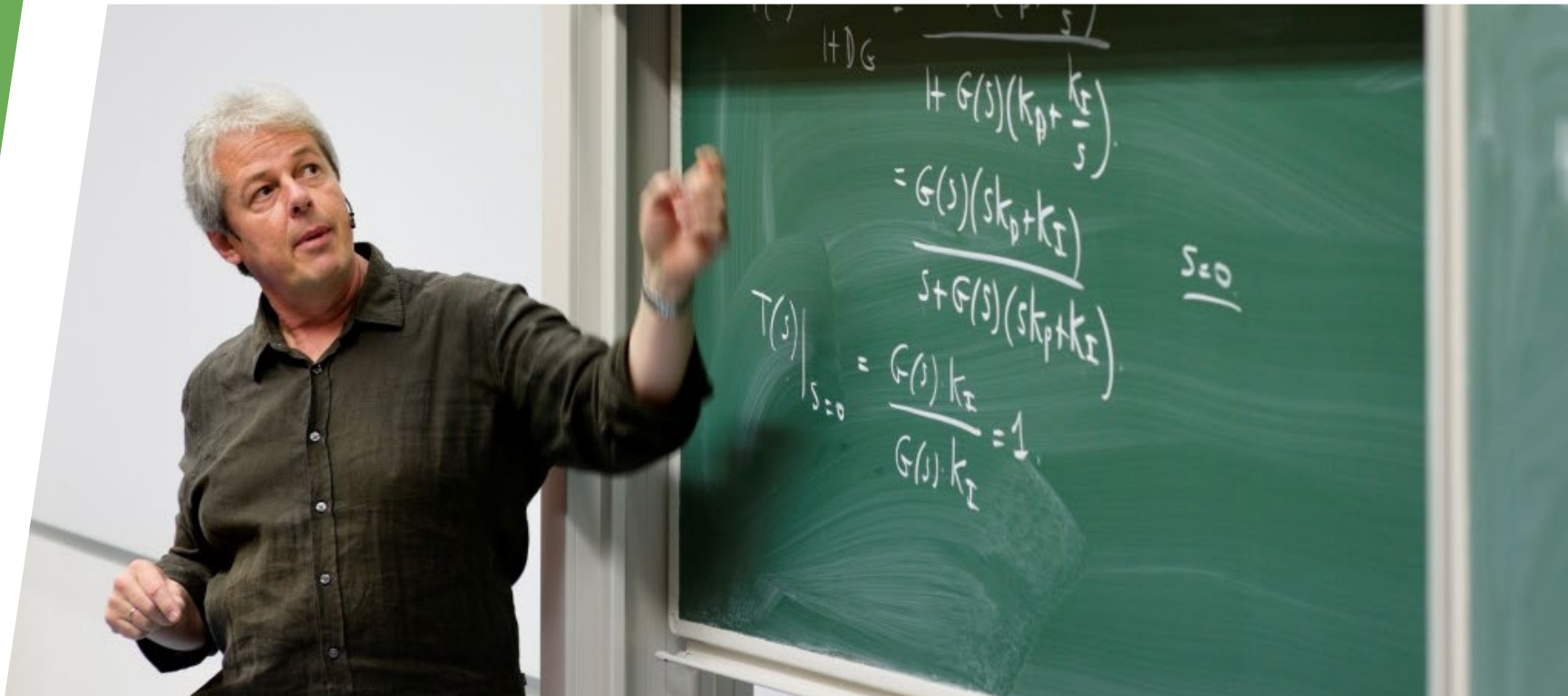
disc dutch institute
of systems
and control

National setting

disc dutch institute
of systems
and control

IFAC2029
amsterdam

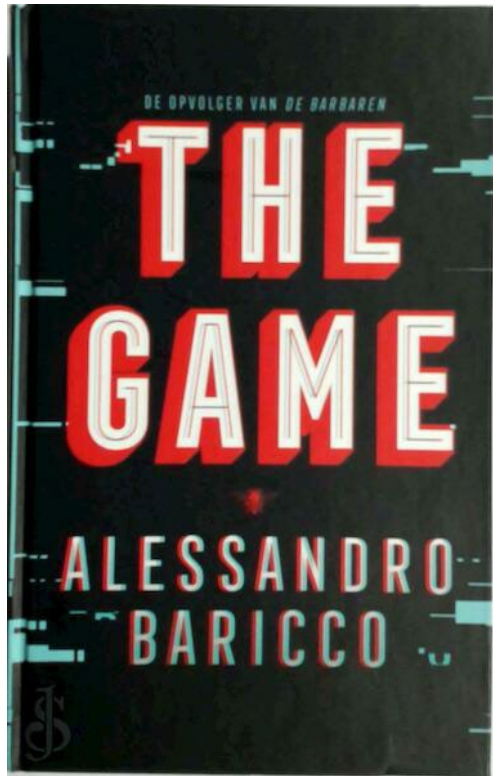




Education

Highly rewarding

Education



2019

Why the cyber world is so much more attractive than the physical world...

Education – Challenge-based learning

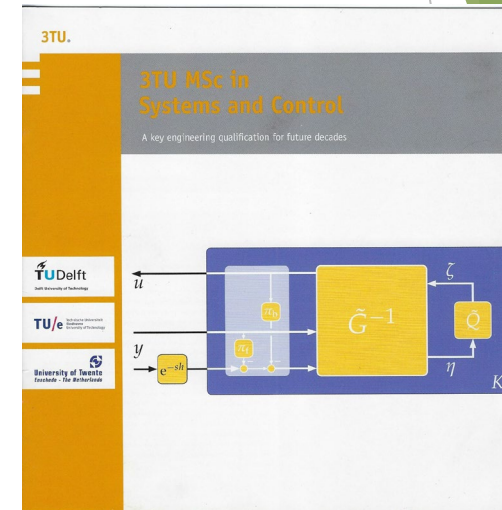
- How to develop analytical skills?
- Which skills are required for engineers in the next decades?

Some university initiatives

- Delft Center for Systems and Control (2003) 

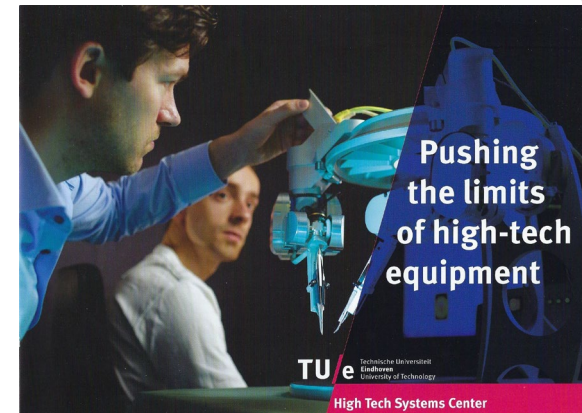
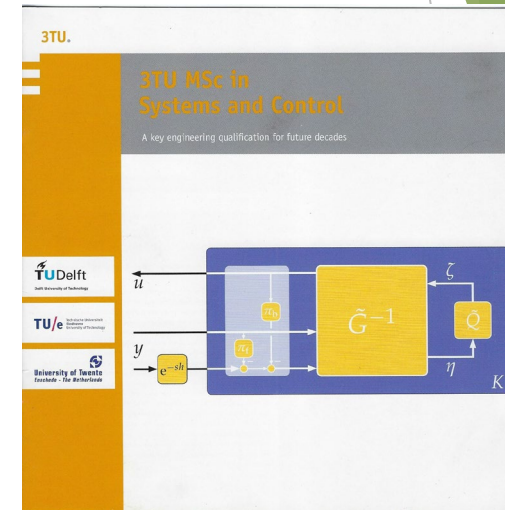
Some university initiatives

- Delft Center for Systems and Control (2003)
- MSc Systems and Control (2004-)
National recognitions, 2010, 2019

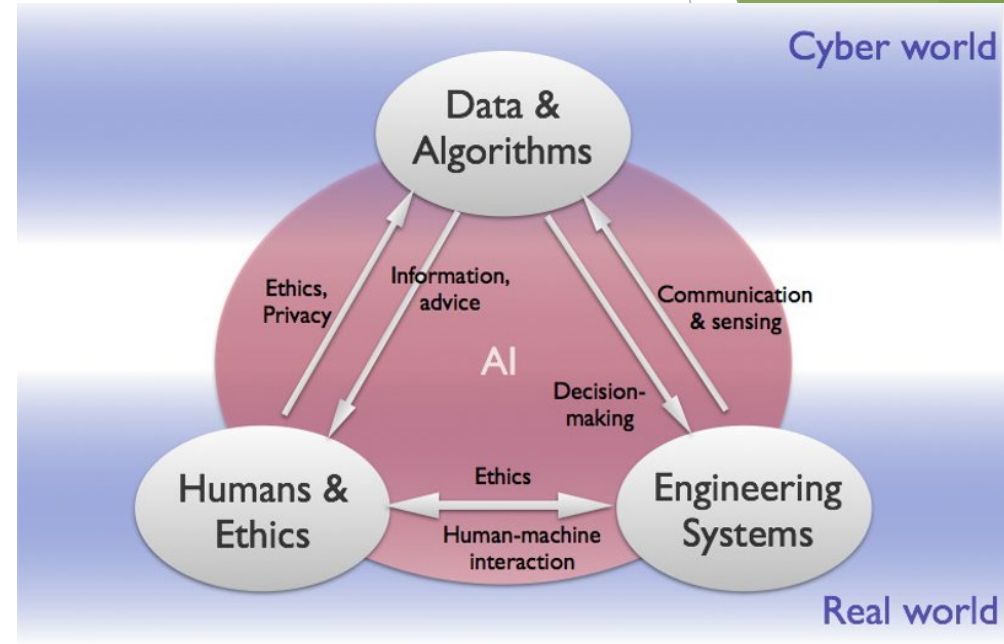


Some university initiatives

- Delft Center for Systems and Control (2003)
- MSc Systems and Control (2004-)
National recognitions, 2010, 2019
- TU/e High-Tech Systems Center (2013)



Some university initiatives



New MSc program

Artificial Intelligence and Engineering Systems (2022 -)

Prospects of the field

- In Eindhoven: > 100 PhD students in control
- Smart production systems, energy transition, robotics, mobility

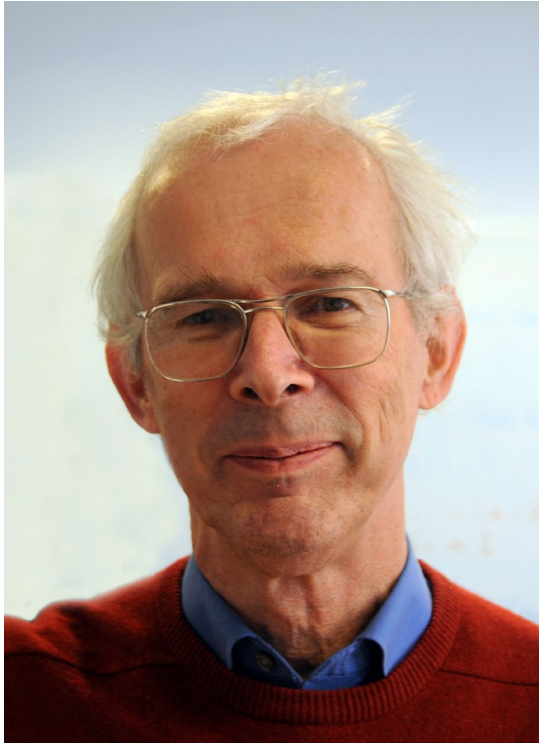
Prospects of the field

- In Eindhoven: > 100 PhD students in control
- Smart production systems, energy transition, robotics, mobility
- Model-based or data-driven ?
- Complex dynamics and large-scale interconnections

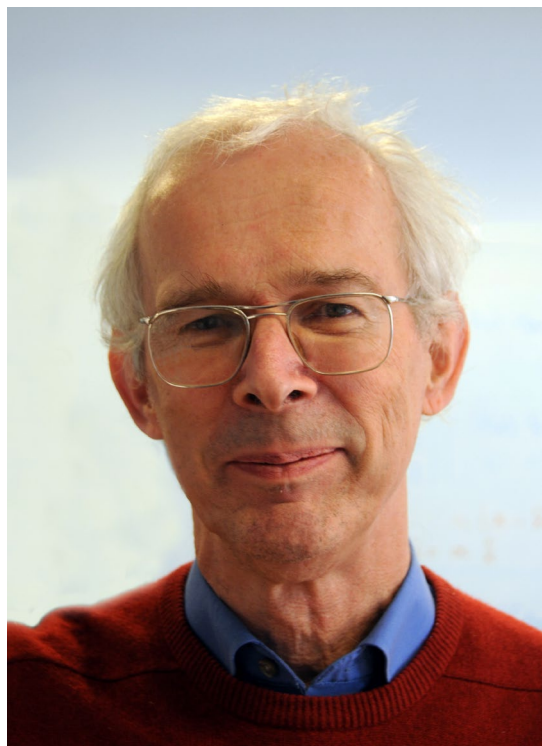
Everything under ~~control~~
AI

Final words and
thanks





Okko Bosgra



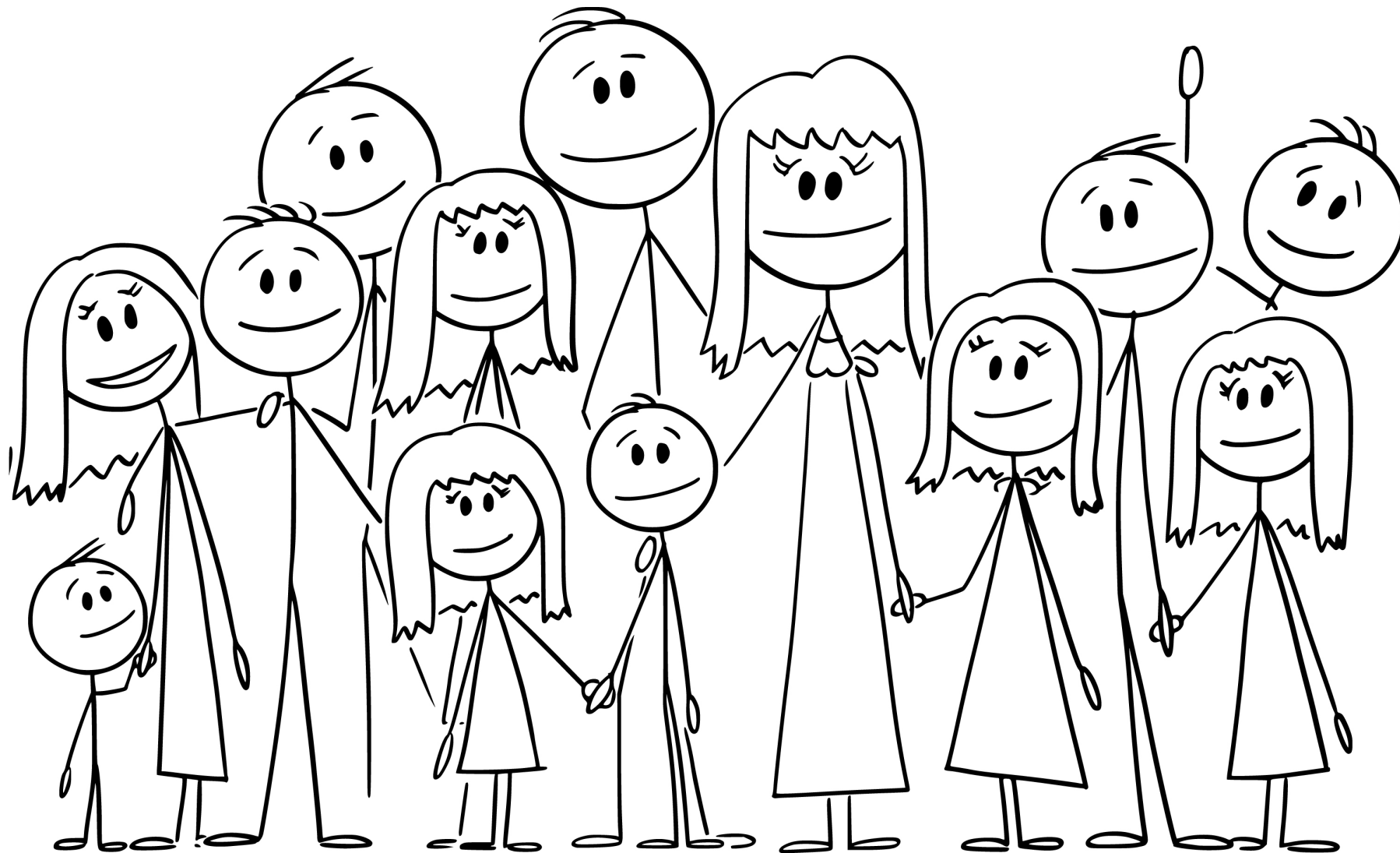
Okko Bosgra



Jan Willems



Thank you



▶ Ik heb gezegd

Prof. Paul M.J. Van den Hof